

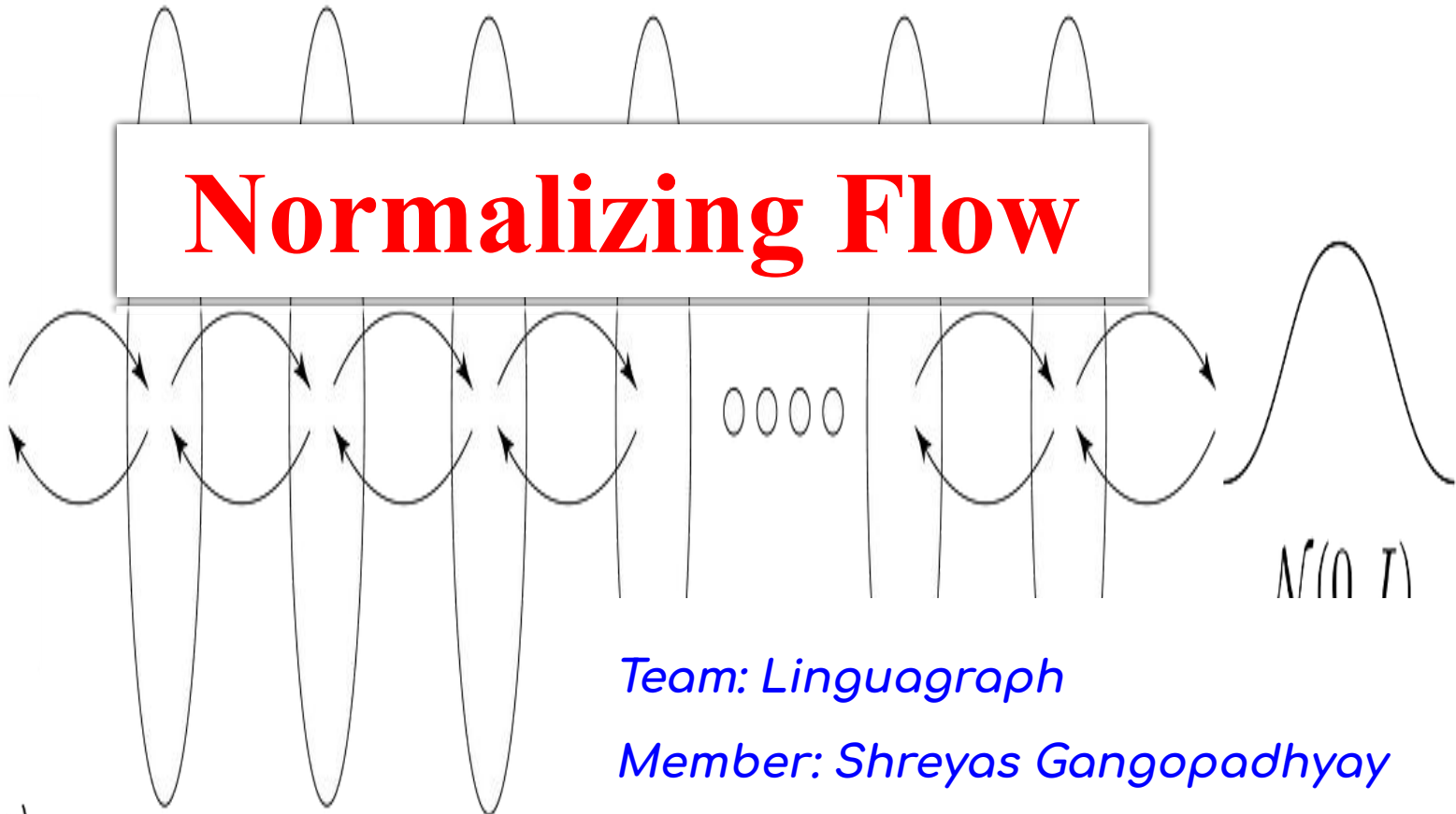
3	4	2	1	9	5	6	2	1	8
8	9	1	2	5	0	6	6	4	
6	7	0	1	6	3	6	3	7	0
3	7	7	9	4	6	6	1	8	2
2	9	3	4	3	9	8	7	2	5
1	5	9	8	3	6	5	7	2	3
9	3	1	9	1	5	8	0	8	4
5	6	2	6	8	5	8	8	9	9
3	7	7	0	9	1	8	5	4	3
7	7	6	4	7	0	4	9	2	3

Dataset

(Complex Distribution)

$f_1$   $f_2$   $f_3$   $f_4$   $f_{n-1}$   $f_n$

# Normalizing Flow



Team: Linguagraph

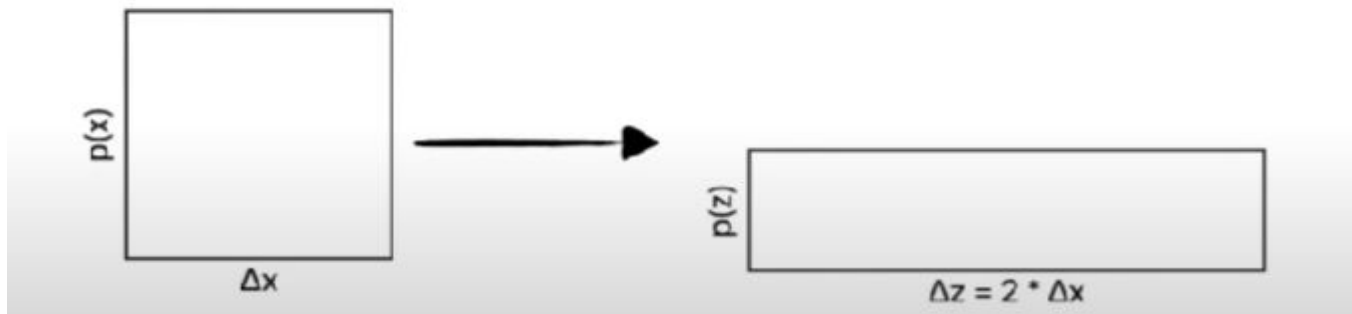
Member: Shreyas Gangopadhyay

# Mapping The Random Variable

$$|p(x)\Delta x| = |P(z)\Delta z|$$

$$p(x) = P(z)|d(z)/d(x)|$$

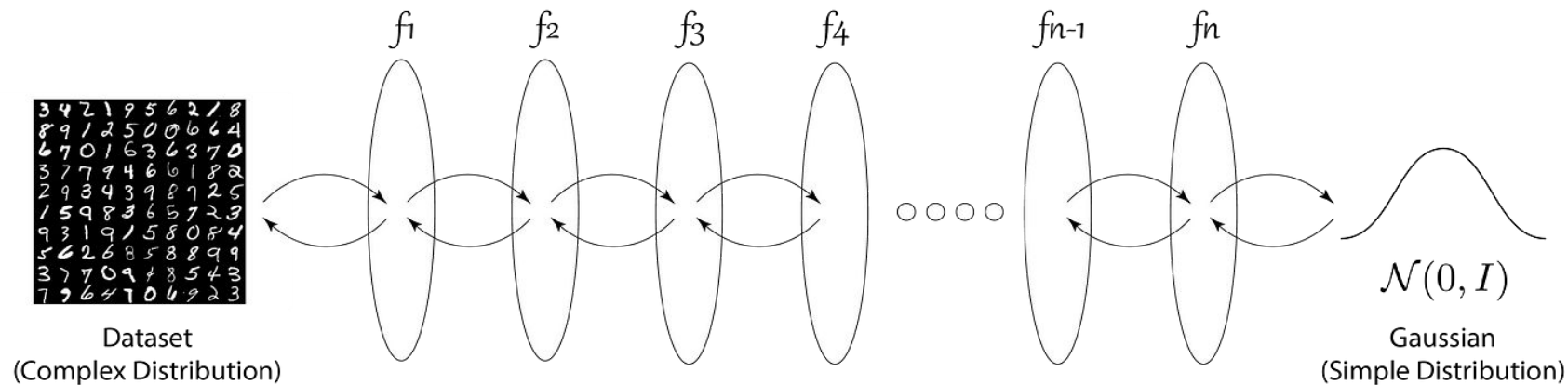
$$\log(p(x)) = \log(P(z)) + \log(|d(z)/d(x)|)$$



# What is Normalizing Flow?

Deep Learning based method to map a one distribution to another one.

The random variable is mapped from one space to another using a series of bijective functions.



## How Does It Work?

$$z \sim P(z) = \mathcal{N}(z; 0, 1)$$

$$x = f(z) = f_1 \dots f_n(z)$$

$f: Z \longrightarrow X$ ,  $f$  is invertible.

**Can we say :  $P_{\Theta}(x) = P_{\Theta}(f^{-1}(x))$  ?**

The answer is **No**.

**Change Of Variables Formula:**

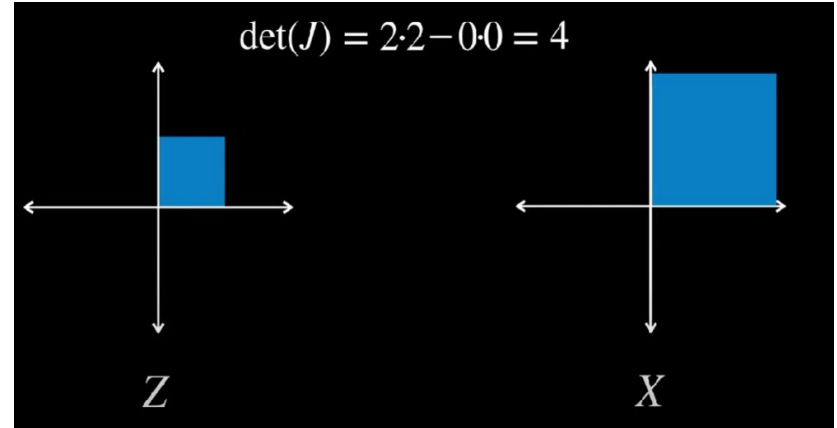
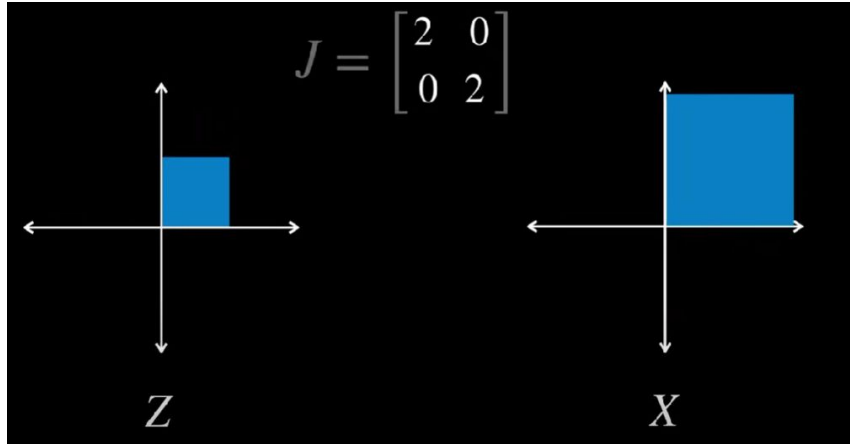
$$P_{\Theta}(x) = P_{\Theta}(f^{-1}(x)) \left| \det(\partial(f^{-1}(x))/\partial(x)) \right|$$

$$\Rightarrow P_{\Theta}(x) = P_{\Theta}(z) \left| \det(\partial(z)/\partial(x)) \right|$$

# Jacobian Determinant

## What does the determinant of Jacobian Signify?

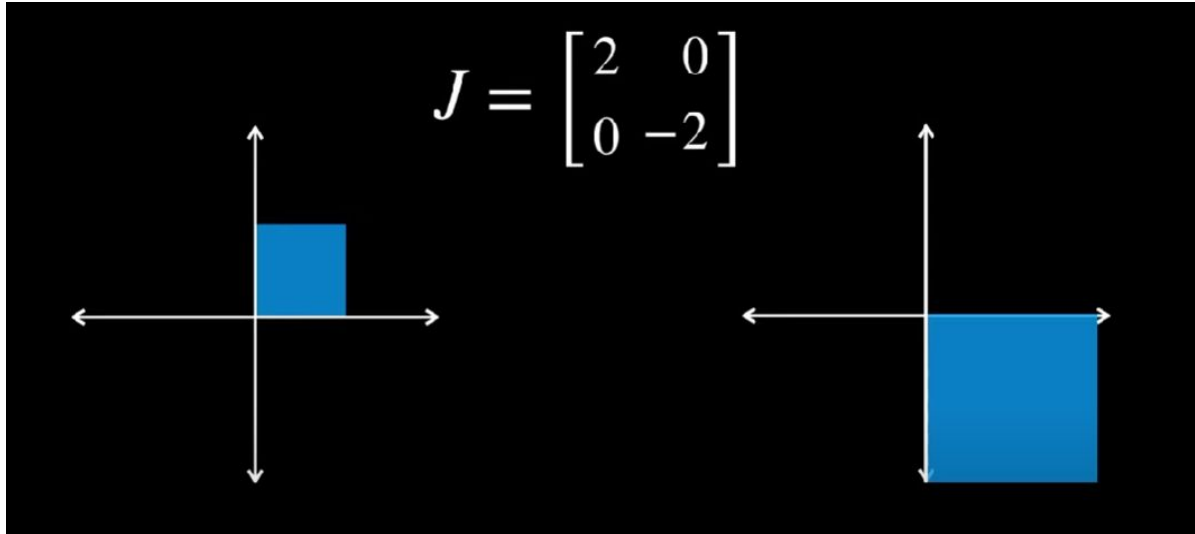
1. The previous equation shows the probability of  $x$  is equal to the probability of  $z$  multiplied by a scalar constant.
2. A probability distribution function must always integrate to 1.
3. The Jacobian determinant signifies how much the transformation contracts or expands a space.
4. This factor ensures that the new density function of  $x$  also satisfies the requirement of  $x$ .



**Note :**  $|\det(\partial(z)/\partial(x))| = |1/\det(\partial(x)/\partial(z))|$

## Another Note:

The orientation of the space is of no consequence because we are taking into account the magnitude of the determinant.





# Log-Likelihood

$$P_{\Theta}(x) = P_{\Theta}(z) \prod |\det(\partial(f_i^{-1})/\partial(x))|$$

Taking Logarithm on both sides:

$$\log(P_{\Theta}(x)) = \log(P_{\Theta}(z)) + \sum \log(|\det(\partial(f_i^{-1})/\partial(x))|)$$

The final objective is to maximise  $\log(P_{\Theta}(x))$ .

# Applications

Normalizing flows can be used to generate new data based on the training data.

For generative models we typically assume:

$z$  to be the latent variables

(We assume the latent variables to be sampled from a normal distribution)

$x$  to be the observed variables.

maximise  $(\log ( P_{\Theta}(z)) + \sum \log (|\det(\partial(f_i^{-1})/\partial(x))|))$



Latent variables sampled from a normal distribution

Model we want to train

## Types of Normalizing Flows

1. Planar Flows : Expands or contracts the distribution along a specific direction.
2. Radial Flows : Modifies the distribution along a certain point.
3. Residual Flows : These use mapping functions like  $g(\mathbf{x}) = \mathbf{x} + F(\mathbf{x})$

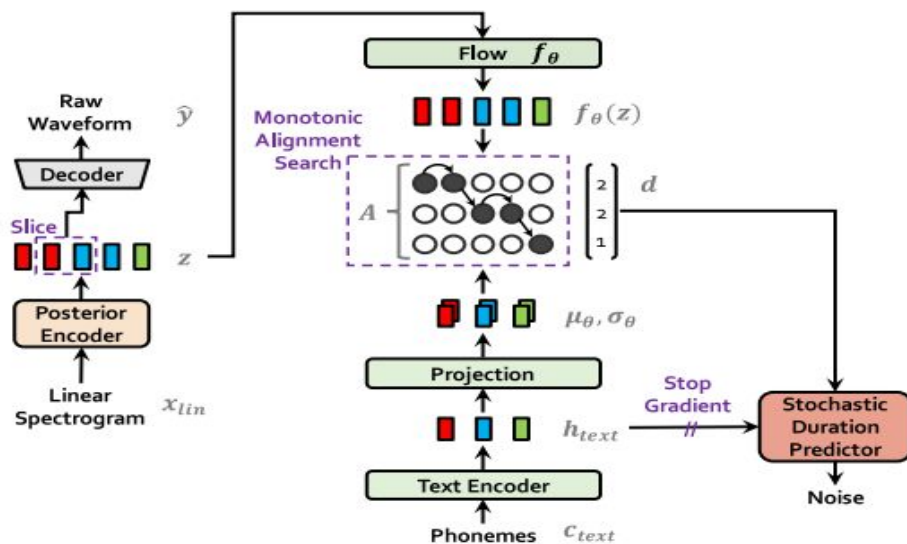
## Case Study : VITS(TTS Model)

**VITS** stand for *Conditional Variational AutoEncoder With Adversarial Training*.

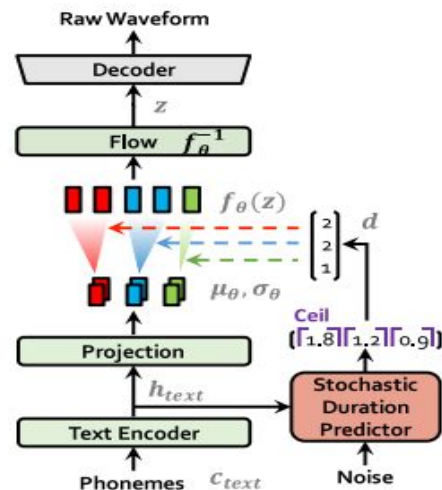
Normalizing Flow finds an application over there, in mapping the simple prior distribution into a more complex distribution to improve expressiveness.

$$p_{\theta}(z|c) = N(f_{\theta}(z); \mu_{\theta}(c), \sigma_{\theta}(c)) \left| \det \frac{\partial f_{\theta}(z)}{\partial z} \right|,$$
$$c = [c_{text}, A]$$

# Architecture of VITS



(a) Training procedure



(b) Inference procedure

**Thank You**